

Indian Institute of Science

ME 261: Midsemester Test

Date: 3/10/15.

Duration: 2.30 p.m.–4.00 p.m.

Maximum Marks: 100

1. Let \mathbf{n} be a unit vector. Find a relation between $[\mathbf{n}, \mathbf{n} \times \mathbf{u}, \mathbf{n} \times \mathbf{v}]$ and $[\mathbf{u}, \mathbf{n}, \mathbf{v}]$. (20)
2. Let $\mathbf{S} = \mathbf{e}_1^* \otimes \mathbf{e}_1^* - 4(\mathbf{e}_2^* \otimes \mathbf{e}_2^* + \mathbf{e}_3^* \otimes \mathbf{e}_3^*)$, where $\{\mathbf{e}_1^*, \mathbf{e}_2^*, \mathbf{e}_3^*\}$ are orthonormal. Find the factors \mathbf{U} , \mathbf{V} and \mathbf{R} in the polar decomposition of \mathbf{S} in terms of \mathbf{e}_1^* and \mathbf{I} . (20)
3. Let $\mathbf{S} \in \text{Sym}$ be invertible, and let $(\lambda_i, \mathbf{e}_i^*)$, $i = 1, 2, 3$, be the eigenvalues/eigenvectors of \mathbf{S} . (30)
 - (a) Find an expression for $\text{cof}(\mathbf{S}^{-1})$ in terms of \mathbf{S} and its invariants.
 - (b) Using this expression, find the eigenvalues/eigenvectors of $\text{cof}(\mathbf{S}^{-1})$.
 - (c) Using the above results determine the following: (i) If \mathbf{S} is positive definite, does it imply that $\text{cof}(\mathbf{S}^{-1})$ is positive definite? (ii) Conversely, if $\text{cof}(\mathbf{S}^{-1})$ is positive definite, does it imply that \mathbf{S} is positive definite? *Justify* your results by providing an example if the result is not true.
4. Let $\phi(\mathbf{x})$ be a function of position \mathbf{x} , and let (30)

$$\boldsymbol{\tau} = (\nabla^2 \phi) \mathbf{I} + \alpha \nabla(\nabla \phi). \quad (1)$$

Determine α so that

$$\nabla \cdot \boldsymbol{\tau} = \mathbf{0}.$$

Substitute the value of α that you have found in Eqn. (1), and determine $\text{tr } \boldsymbol{\tau}$ in terms of ϕ . Substitute this equation into

$$\nabla^2(\text{tr } \boldsymbol{\tau}) = 0,$$

to get a governing equation for ϕ . Determine if $\phi = \mathbf{x} \cdot \mathbf{x}$ satisfies this governing equation that you have determined.

Some relevant formulae

$$(\text{cof } \mathbf{T})^T \mathbf{T} = (\det \mathbf{T}) \mathbf{I}.$$